

# Efficient Algorithms for Graph Sparsification

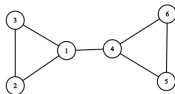
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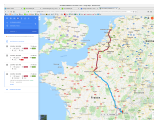
Joint with **Simon Apers** (INRIA & CWI)

# Graphs



- ▶ Big part of discrete mathematics
- ▶ Graphs model many important phenomena:

- ▶ Logistics



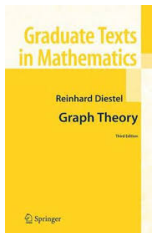
- ▶ Internet



- ▶ Social networks



- ▶ **Sparse** graphs are better than dense graphs:
  - ▶ Need less **space** to store
  - ▶ Need less **time** to operate on



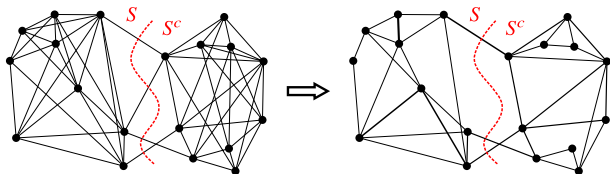


## Sparsifiers preserve all cuts in the graph

- ▶ An  $\varepsilon$ -spectral sparsifier of  $G = (V, E, w)$  is a graph  $H = (V, E', w')$  s.t. for all  $x \in \mathbb{R}^n$  :  $x^T L_G x = (1 \pm \varepsilon) x^T L_H x$
- ▶ Special case: consider  $x \in \{0, 1\}^n$ , with support  $S$ .  
 $x^T L_e x = 1$  if edge  $e$  is cut, 0 otherwise. Hence

$$x^T L_G x = \sum_e w(e) x^T L_e x = \sum_{e \in S \times S^c} w(e)$$

is the value of the cut  $S, S^c$ . So  $H$  preserves all cuts of  $G$ !

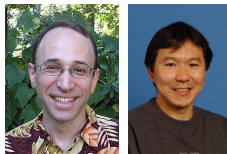


## Good sparsifiers exist & are cheap to find!

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- ▶ How sparse can we make  $H$ ?  
 $|E'| \approx n/\varepsilon^2$  edges are necessary and sufficient
- ▶ How quickly can we find such an  $H$ ?  
Near-linear time in the input length!  $\tilde{O}(m)$  time  
(input given as adjacency list for each vertex)
- ▶ Many applications

Gödel Prize 2015 for  
Dan Spielman and Shang-Hua Teng



## Applications (non-exhaustive list)

General idea to operate efficiently on graphs: first sparsify input graph  $G$ , then run your best algorithm on the sparsifier  $H$

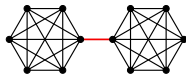
- ▶ Approximating **min-cut** in near-linear time
- ▶ Approximating **max-cut** up to the Goeman-Williamson ratio of 0.878 in near-linear time (better approximation is hard)
- ▶ **Partitioning** a graph: find min-cut and partition recursively
- ▶ **Laplacian solving**: given symmetric, diagonally-dominant  $n \times n$  matrix  $L$  with  $m$  nonzero entries, and  $b \in \mathbb{R}^n$ , find  $x$  s.t.  $Lx = b$ . Can solve this approximately in time  $\tilde{O}(m)$ : massage  $L$  to Laplacian  $L_G$  of a graph, sparsify, solve  $L_H x = b$

Remarkable: few other problems solvable in near-linear time

# How to efficiently compute a sparsifier

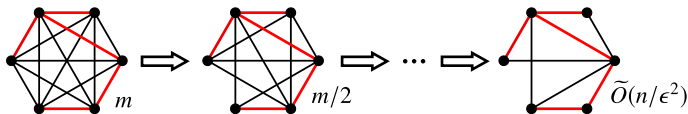
- ▶ Long line of work. We'll describe approach due to Koutis-Xu'16, which repeatedly cuts number of edges in half

- ▶ Some edges are more important than others:



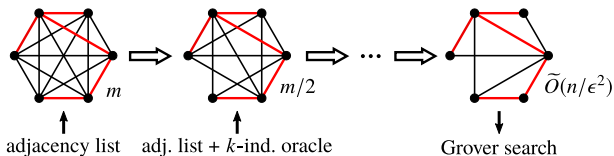
- ▶ Idea: identify most important edges by finding  $O(\log(n)^2/\epsilon^2)$  disjoint **spanners** of  $G$  (preserve distances, linear-time comp.) Keep their edges in the sparsifier, plus a **random sample** of half of remaining edges reweighted by factor 2. This gives a sparsifier with  $\approx m/2$  edges.

- ▶ Iterate this log times to reduce  $m$  to  $\tilde{O}(n/\epsilon^2)$  edges



# Faster **quantum** algorithm for sparsification

- ▶ Apers & dW'19: **quantum** algorithm to find  $\varepsilon$ -spectral sparsifier  $H$  in sublinear time  $\tilde{O}(\sqrt{mn}/\varepsilon)$  (this is **optimal!**)
- ▶ Similar speed-up for cut problems, Laplacian solving etc.
- ▶ We speed up Koutis-Xu using two quantum tools: find spanners in time  $O(\sqrt{mn})$ , and find the final set of  $\tilde{O}(n/\varepsilon^2)$  edges using Grover's quantum search algorithm

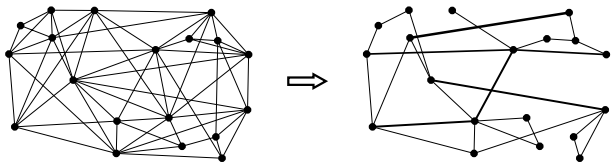


- ▶ This gives an  $\tilde{O}(\sqrt{mn}/\varepsilon^2)$ -algorithm. Improve  $\varepsilon$ -dependence via Spielman-Srivastava'11 (based on “effective resistances”)



# Summary

- ▶ Given any weighted graph  $G$ , in near-linear time we can compute a sparse graph  $H$  that approximately preserves most properties of  $G$



- ▶ Leads to near-linear time algorithms for many cut problems, graph partitioning, Laplacian linear system solving, ...
- ▶ Apers & dW'19: quantum computer can do it even faster